

Graph Drawing using the Laplacian

Based on Spielmann, Chapter 3

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Overview

- 1 Embedding a graph into the line
- 2 One dimensional artwork
- 3 Embedding a graph into the plane
- 4 Two dimensional artwork
- 5 Three dimensional artwork

Embedding a graph to \mathbb{R}

$$\chi: V \rightarrow \mathbb{R}$$

Say we wish to embed a graph G to the reals. How should we go about it? Connected vertices should be close, so we can express this as minimizing

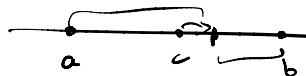
$$\mathbf{x}^T \mathbf{L} \mathbf{x} = \sum_{uv \in E} (\mathbf{x}(u) - \mathbf{x}(v))^2,$$

where \mathbf{x} is the embedding.

Question

What is the obvious issue with this suggestion?

Embedding a graph to \mathbb{R}



So we normalize so that the points in \mathbf{x} are not too concentrated around any point.

$$\forall p \in \mathbb{R} \quad \sum_{v \in V} (\mathbf{x}(v) - p)^2 \geq 1.$$

Question

What can we say about p ?

Embedding a graph to \mathbb{R}

So we normalize so that the points in \mathbf{x} are not too concentrated around a point.

$$\forall p \in \mathbb{R} \quad \sum_{v \in V} (\mathbf{x}(v) - p)^2 \geq 1.$$

$$p = \mathbb{E}_v \mathbf{x}(v) = \mathbf{u}^T \mathbf{x}$$

where $\mathbf{u} = \frac{1}{n} \cdot \mathbf{1}$. By shifting, we may as well assume $\mathbf{u}^T \mathbf{x} = 0$.

Embedding a graph to \mathbb{R}

Hence, we want to minimize $\mathbf{x}^T \overset{L}{\mathbf{M}} \mathbf{x}$ subject to $\mathbf{u}^T \mathbf{x} = 0$ and $\|\mathbf{x}\|_2 = 1$.

Question

Who is \mathbf{x} ?

ψ_2

Examples



$$\sum (x^{(i+1)} - x^{(i)})^2$$

Figure: 20-vertex path graph embedded into \mathbb{R} .

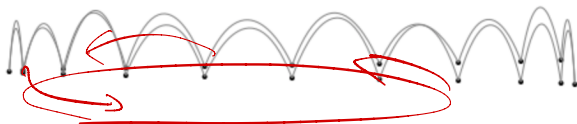


Figure: 20-vertex cycle graph embedded into \mathbb{R} .

(function on \mathbb{R})

Examples



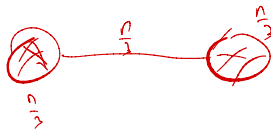
Figure: Depth-4 complete binary tree embedded into \mathbb{R} .



Examples



Figure: Third-dumbbell embedded into \mathbb{R} .



Examples

$$\sum_{u,v} (x(u) - x(v))^2$$



Figure: 5-clique embedded into \mathbb{R} .

Examples

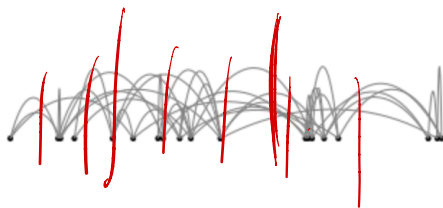


Figure: Degree 2 plus symmetrization random graph embedded into \mathbb{R} .

My modest code

```

using LinearAlgebra
using Plots
using Luxor

function draw_on_line(M)
    n = size(M)[1]
    E = eigen(M)
    v2 = E.vectors[:,n-1]
    s = 300

    @png begin
        for i in 1:n
            circle(Point(s*v2[i],0),2,:fill)
        end

        sethue("gray")
        setline(1)
        for i in 1:n
            for j in i:n
                if (M[i,j] == 1)
                    A = Point(s*v2[i], 0)
                    B = Point(s*v2[j], 0)
                    C = Point((A.x+B.x)/2,-80+rand(-40:1:40))
                    curve(A, C, B)
                    strokepath()
                end
            end
        end
    end

    P = clique_no_loops(10)
    plot!(P)
end

```

Drawing a graph on the plane

Moving to two dimensions, we now wish to find a pair $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ that minimizes

$$\sum_{uv \in E} \left\| \begin{pmatrix} \mathbf{x}(u) \\ \mathbf{y}(u) \end{pmatrix} - \begin{pmatrix} \mathbf{x}(v) \\ \mathbf{y}(v) \end{pmatrix} \right\|_2^2 \quad (1)$$

subject to $\mathbf{u}^T \mathbf{x} = \mathbf{u}^T \mathbf{y} = 0$ and $\|\mathbf{x}\| = \|\mathbf{y}\| = 1$.

$$(1) = \mathbf{x}^T \mathbf{L} \mathbf{x} + \mathbf{y}^T \mathbf{L} \mathbf{y}$$

(Handwritten red text: "this is the same as the sum of squares of the edges")

$$\mathbf{u} = \begin{pmatrix} -1/\sqrt{2} \\ \vdots \\ -1/\sqrt{2} \end{pmatrix}$$

Question

What other condition you would suggest we include?

This is precisely Hall's idea.

$$\mathbf{x}^T \mathbf{y} = 0$$

A lower bound

$$\psi_2^T L \psi_2 + \psi_3^T L \psi_3 = \lambda_2 + \lambda_3$$

Theorem

Let \mathbf{L} be a Laplacian matrix. For $k \geq 1$ let $\mathbf{x}_1, \dots, \mathbf{x}_k$ be orthonormal vectors that are all orthogonal to $\mathbf{1}$. Then,

$$\sum_{i=1}^k \mathbf{x}_i^T \mathbf{L} \mathbf{x}_i \geq \sum_{i=2}^{k+1} \lambda_i.$$

Some room for the proof

$$x_i^T L x_i = \sum_{j=2}^n \lambda_j (\psi_j^T x_i)^2$$

$$x_i \perp \psi_1 \rightarrow = \lambda_{k+1} + \sum_{j=2}^n (\lambda_j - \lambda_{k+1}) (\psi_j^T x_i)^2$$

$$(\text{red}) = \sum_{j=2}^n (\psi_j^T x_i)^2$$

$$0 = \lambda_1 \leq \lambda_2 \leq \dots$$

$$\geq \lambda_{k+1} + \sum_{j=2}^{k+1} (\lambda_j - \lambda_{k+1}) (\psi_j^T x_i)^2$$

$$\sum_{i=1}^k x_i^T L x_i \geq k \lambda_{k+1} + \sum_{j=2}^{k+1} (\lambda_j - \lambda_{k+1}) \underbrace{\sum_{i=1}^k (\psi_j^T x_i)^2}_{\leq \|\psi_j\|_2^2 \leq 1}$$

$$\geq k \lambda_{k+1} + \sum_{j=2}^{k+1} (\lambda_j - \lambda_{k+1}) \cdot 1$$

Examples

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AN r -DIMENSIONAL QUADRATIC PLACEMENT ALGORITHM*

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State of California, Department of General Services

In this paper the solution to the problem of placing n connected points (or nodes) in r -dimensional Euclidean space is given. The criterion for optimality is minimizing a weighted sum of squared distances between the points subject to quadratic constraints of the form $X'X = 1$, for each of the r unknown coordinate vectors. It is proved that the problem reduces to the minimization of a sum of r positive semi-definite quadratic forms which, under the quadratic constraints, reduces to the problem of finding r eigenvectors of a special "disconnection" matrix. It is shown, by example, how this can serve as a basis for cluster identification.

Examples

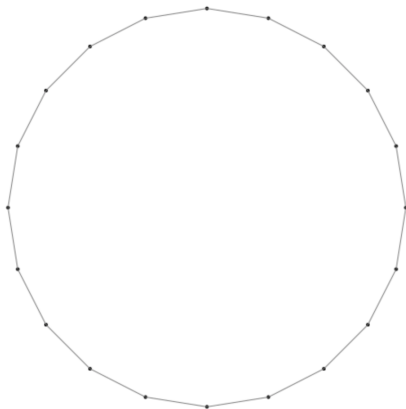


Figure: 20-cycle embedded into \mathbb{R}^2 .

Examples

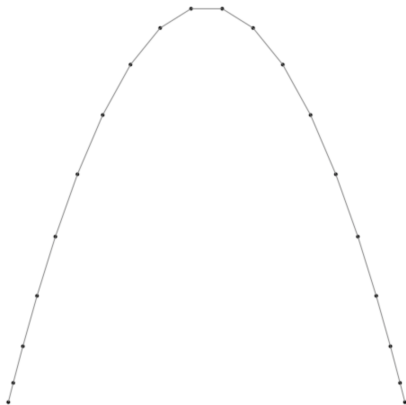


Figure: 20-vertex path embedded into \mathbb{R}^2 .

Examples

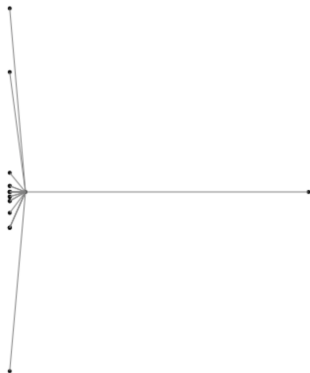


Figure: 20-vertex star graph embedded into \mathbb{R}^2 .

Examples

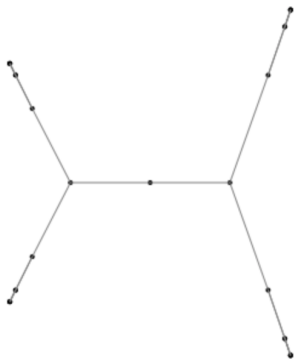


Figure: Depth-4 complete binary tree embedded into \mathbb{R}^2 .

Examples

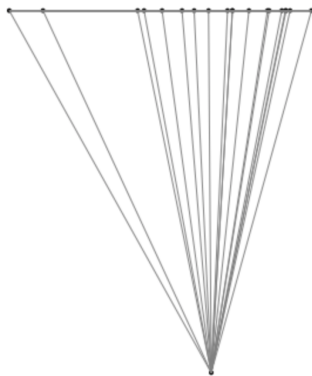


Figure: 20-vertex clique embedded into \mathbb{R}^2 .

Examples

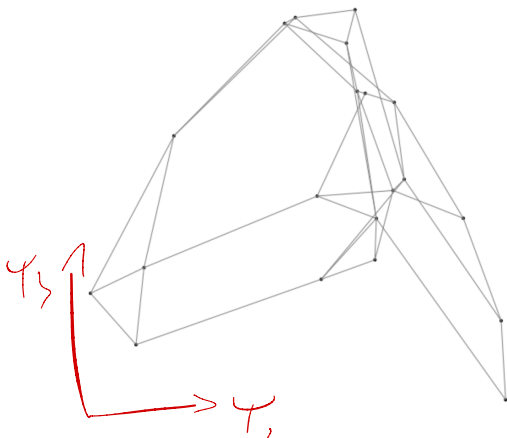
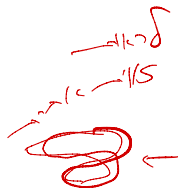
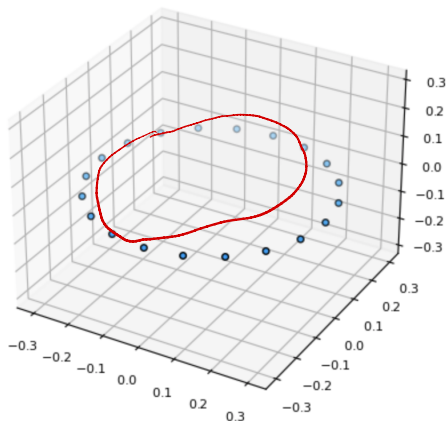


Figure: 20-vertex random graph (degree 2 symmetrized) embedded into \mathbb{R}^2 .

Going 3D!

Figure: 20-cycle embedded into \mathbb{R}^3 .

Going 3D!

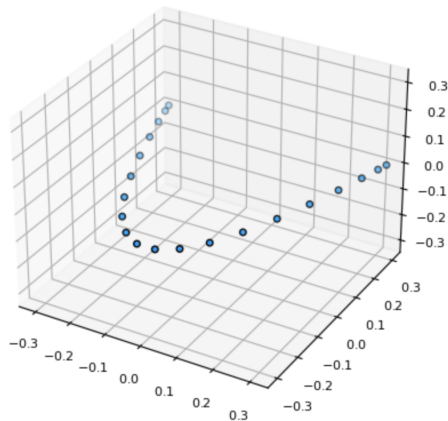


Figure: 20-vertex path embedded into \mathbb{R}^3 .

Going 3D!

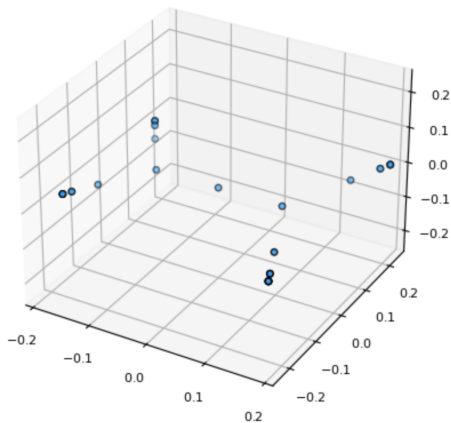


Figure: Depth-4 complete binary tree embedded into \mathbb{R}^3 .

Going 3D!

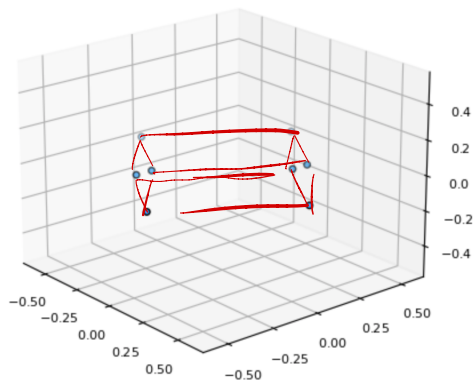


Figure: Who am I?

My modest code

```
function draw3d(M)
    n = size(M)[1]
    E = eigen(M)
    v2 = E.vectors[:,n-1]
    v3 = E.vectors[:,n-2]
    v4 = E.vectors[:,n-3]
    Plots.scatter(v2, v3, v4, leg = false, camera = (50,20))
end

draw3d(lap(cube()))
```